Programs for the HP-28 calculator



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A Brief Introduction into Programming the HP-28*

The programs in this book use the more fundamental commands of the HP-28 language. These are the loop commands START-NEXT and FOR-NEXT and the IF-THEN-END command.

Before we talk about how these commands work, let's discuss a few fundamental points.

From the point of view of the calculator, anything enclosed in the double-arrow brackets « and » is considered a program. For example « "Hello, world" 1 DISP ». This uses the DISP (display) command to print Hello, world at the top of the screen.

Suppose you want to write a program that takes any number given to it and multiplies it by 5 then subtracts 3. The first thing you need to do is to be able to input or "grab" a number. This is done with the → command (the shifted U on the left side keyboard). This command is used in conjunction with what are called "local variables" like this: The "a" is the local variable. Local variables differ from "global" variables (the other kind) in that they are only used for one calculation or procedure (which HP calls a defining program but "procedure" is more to the point) and then they are thrown away. By contrast, a global variable is stored under a name in a USER menu. For example, if you put the number 10 on the stack and did this: 'A' STO , under the USER menu you would see [A] for a function key. This "global" variable doesn't disappear unless you PURGE it! This brings up another point; notice that the lower case letters are used for local variables and the upper case letters are used for global variables. This is done by convention so you know which are which.

Anyway, back to our program. We can write it three ways:

After typing in one of the programs you would store it under your favorite name. Then you could put any number on the stack and press the function key labeled with the name you chose (under USER) and, presto!, the result will appear. One thing you may have noticed is that while the first program is "readable" the second program looks like a mistake. Thats because the first program uses an expression which is anything enclosed in single quotes. expression is written just the way you would write it on paper. Since the expression in the first program comes after the inputted variable with no other brackets, it is evaluated immediately. The second program just carries out the button pushing as if you did the function manually on the calculator and remember it's Reverse polish notation. program looks like the first program except for the extra set of brackets. If you did not have the EVAL command in the third program, the program would just put 'a * 5 - 3' on the stack unevaluated.

As a rule of thumb, when you input a number into a variable, you <u>must</u> use « » around whatever follows that uses the variable. Like this:

This way you don't have to worry about using the local variable more than once. For example, the following program won't work:

 $\ll \rightarrow k 'k + 5' 'k - 2' >$

The first expression is evaluated, but then the local variable is gone! So the second expression is put on the stack as-is. However, the following program does work:

 $\ll + k \ll 'k + 5'$ EVAL 'k - 2' EVAL » »

The inside set of brackets defines everything inside of them as one procedure. Therefore, the local variable is good for everything inside them. Notice that the programs in this book are laid out in a way so you can see the *structure* or organization of the program better. You don't have to type them in to *look* like this (you probably couldn't). The calculator will squash them up anyway after you ENTER the program. You only need to pay attention to spaces around command words. For example, →k is wrong it should be → k. Also, → ARRY is wrong, it should be →ARRY.

Program comments that are on the right side of program listings in this book are in italics. These are comments ONLY! Don't type them into the calculator.

Now for the basic loops. Lets look at the START-NEXT loop. It has the form of:

a b START

stuff

NEXT

The stuff is any set of commands you want repeated. a and b are the beginning and ending numbers for the loop. For example if you wanted to go through the loop 3 times a and b would be 1 and 3, 10 and 12, 22 and 24, etc.

The FOR-NEXT loop is the same except you can define a local variable which is given the value of the present loop. The value (an integer) of the present loop is called the index.

Example:

« 1 10 FOR x 'x * 2' EVAL NEXT

The variable of your choice is defined when it is placed directly after the FOR statement, in this case FOR x. Notice that x is used in the expression 'x*2' and evaluated 10 times, putting 10 numbers on the stack.

You can change the increment of the index from 1 (default when using NEXT) to any number you choose by replacing NEXT with increment number STEP. For example, 2 STEP causes 2 to be added to the index. You can also have the loop count from a high number down to a low number by having a > b and using a negative increment number. STEP can also replace NEXT in the START-NEXT loop.

The other important statement is the IF-THEN-END statement. It has the form:

IF something
THEN
stuff
END

The something is a statement that tests something to see if it's true. For example, IF y > 5. If $y \stackrel{is}{=}$ greater than 5 (True) then carry out the stuff. If $y \stackrel{is}{=}$ not greater than 5 (False) then continue program right after the END statement.

There is also a variation called IF-THEN-ELSE-END in which the form is:

IF something
THEN
stuff
ELSE
different stuff
END

In this case the different stuff is carried out if the something is false.

Many of the programs in this book use the IFERR-THEN-END statement (If error). It has the form:

IFERR
stuff
THEN
different stuff
END

If the *stuff* commands are carried out normally, the program continues after the END statement (skips the *different stuff*). If an error occurs while carrying out *stuff*, then the *different stuff* commands are executed. The IFERR statement is used in some of the programs in this book as a way to display a help message:

IFERR
program with an input.
THEN
display help screen
END

This is very handy, because frequently you forget what a program does or what variables are required for input. As structured above, you could just hit the program key and the program would error-out because it was expecting a numeric input, and would then display the help screen.

You will find that the other loops and branch commands are variations and combinations of the above forms. Hopefully, the programs in this book will help you to learn how to program the HP-28 by example and give you a sense of how much time and busy work can be saved by writing useful programs.

Quadradic formula program.

The quadradic formula takes coefficients from a polynomial of the form:

```
ax^2 + bx + c = 0
```

and gives the roots (zeros) of the equation.

Example use (program name: [QUADR])

for $2x^2 + 3x + 4$.

Press [QUADR].

Type 2,3,4 on command line.

Press [CONT].

>>

The program displays the answer.

program listing [QUADR]

Comments

Clear stack.

Prompt user.

```
« CLEAR CLLCD
" Quadradic Formula " 1 DISP
" Enter a,b,c, then " 2 DISP
" press continue " 3 DISP
HALT
→ a b c
  (-b + \int (b^2-4*a*c))/(2*a) EVAL
   «
   IF y IM 0 > THEN
     CLLCD
      " Imaginary roots are" 1 DISP
      y RE 2 DISP
      " + or - i" 3 DISP
     y IM 4 DISP
   ELSE
      CLLCD
      " Real roots are " 1 DISP
      (-b - \int (b^2-4*a*c))/(2*a)
     EVAL
      → Z
      « y 2 DISP
        " and " 3 DISP
       z 4 DISP
   END
  >>
 >>
```

End of program.

Song program.

Make a list of the form { n tone duration tone duration} where n is the number of tone-duration pairs. The following program will play the song.

Example use (program name [PLAY])

Put list in level 1 (see example below). Press [PLAY]

program listing

comments

```
« DUP
                                         Duplicate list.
1 GET → s
                                    Grab n from list.
 « 2 1 s START
  GETI → a
                                         Grab tone.
                                         Grab duration.
    « GETI → d
     « 'a' EVAL 'd' EVAL BEEP »
                                         play tone.
  NEXT
                               Repeat until end of list.
 >>
                                         The End.
>>
```

example songs:

```
{ 11 560 .4 560 .3 560 .1 560 .4 660 .3 620 .1 620 .3 560 .1 560 .3 525 .1 560 .5 }
```

{ 15 440 .4 580 .3 580 .05 580 .4 650 .4 730 .3 730 .05 730 .6 730 .1 650 .1 730 .1 765 .4 550 .4 650 .4 580 .4 }

<u>Linear Algebra Programs</u>

The matrix in the following programs is stored in the global variable X.

3

```
Row operation program
This program performs the row operation
      g*ROW_h + ROW_i ---> ROW_j.
(g,h,i,j is sequence on command line.)
Example use ( program name [RWOP] )
Put a matrix on stack, level 1:
       [[ 1 3 6 4 ]
        [ 3 -4 2 2 ]
        [ 1 2 3 4 ]
        [ 2 0 3 4 ]]
Type in -2,3,4,4 on command line.
Press [RWOP].
This is: -2 times row 3 plus row 4 and put result in
row 4.
program listing [RWOP]
\ll \rightarrow g h i j
  « 'X' STO
     X SIZE LIST→ DROP
                        → r c
    « 1 c FOR d
           X { h d} GET g *
          NEXT
           \{1c\}\rightarrow ARRY
       1 c FOR d
```

X { h d} GET g *

NEXT

{ 1 c } →ARRY

1 c FOR d

X { i d } GET

NEXT

{ 1 c } →ARRY +

'Y' STO

1 c FOR d

Y { 1 d } GET

X { j d } ROT PUT

'X' STO

NEXT

X

'Y' PURGE

>>

>>

```
Row Swap Program
    Swaps two rows.
Example use ( program name [RRSW] )
Put matrix on stack, level 1.
Type in 2,4 on command line.
Press [RRSW].
This swaps rows 2 and 4.
program listing [RRSW]
«
 → h i
    «
       'X' STO
       X SIZE LIST→ DROP → r c
        «
          1 c FOR d
                X {i d} GET
              NEXT
                {1 c} →ARRY
                'Y' STO
          1 c FOR d
                Y {1 d} GET
                X {h d} GET
                X {h d} 4 ROLL PUT
                {i d} 3 ROLL PUT
                'X' STO
              NEXT
              X
              'Y' PURGE
          >>
```

>>

»

```
Row Multiply/Divide program
Multiplies (divides) a row by a number.
Example use ( program name [RMLT] ( [RDIV] ))
Put matrix on stack, level 1.
Type in -6,3 on command line.
Press [RMLT]. ( [RDIV] )
This multiplies (divides) row 3 by -6.
program listing
«
   → g h
     «
        'X' STO
        X SIZE LIST→ DROP → r c
          1 c FOR d
                X {h d} GET g *
                                   <<NOTE: change * to
                                     / for [RDIV]
              NEXT
              \{1 c\} \rightarrow ARRY
                                      program.
              'Y' STO
          1 c FOR d
                Y {1 d} GET
                X {h d} ROT PUT
                'X' STO
              NEXT
              X
              'Y' PURGE
          >>
      >>
>>
```

To make the two different programs: type in the program listing above; store as [RMLT]; then RCL and RDIT it, and replace the * with /; then store this new version as [RDIV].

Synthetic Division Program

A polynomial:

 $f(x) = a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x + a_0$ has possible rational roots equal to:

Use synthetic division on the equation f(x) to determine if each possible root produces a remainder of 0 when divided into f(x).

The <u>remaining</u> roots are true factors of the "residue equation" that the previous true factor produced after division.

[-2] 3 14 14 -8 -8
+. -6 -16 4 8
residue eq.-> 3 8 -2 -4 0 <--- shows that -2
(not including 0) is a root of

$$3x^4+14x^3+14x^2-8x-8$$
.

Example use (program name [SYNTH])

Enter the coefficients of the polynomial as a vector in level 1.

Type in the root you what to try -2. Press [SYNTH].

The program puts the residue equation and remainder on the stack, and stores the original vector in X.

If the remainder is 0 (a root is found), then [DROP] the zero, enter the next possible root, and press [SYNTH].

If the remainder is NOT zero (not a root) then [CLEAR] the stack and press [X] to bring up your original vector. Then try next possible root.

program listing [SYNTH]

```
→ C
        «
            'X' STO
            X SIZE LIST→ DROP → j
                     X 1 GET DUP c *
               2 j FOR i
                     X i GET +
                     DUP
                     c *
                   NEXT
                   DROP → r
                    «
                       DEPTH
                        →ARRY
                     >>
               >>
           >>
>>
```

Data Bank Programs

The following programs should be put in their own sub-directory. A sub-directory can be made , for example, by typing:

'DATA'

[CRDIR]

Name of sub-directory

Command "Create Directory"

found under MEMORY menu.

[DATA] will now be a key in the USER menu. Press [DATA] to get into the DATA sub-directory. The user keys go blank, indicating that there is nothing in the sub-directory DATA. Now type the following:

Now you have [RTN] for a user key. When you press [RTN], it returns to the HOME or Root directory. This is just a simple way to pop back and forth between your sub-directories and the HOME directory.

```
The Data bank programs scroll through a list of data. Create a list like the following:

{ "Bob 123-4567" "Joe 234-5678" "Fred 567-3456" "John 444-5555" "Carol 555-2323" }
```

Then store the list under the name 'Q':

'Q' [STO]

The programs also uses an index number which is stored under the name 'N'. So you need to create that also:

```
1 [ ENTER ] Start out with an index of 1.
'N'
[STO]
```

Now the only thing left is the following 2 programs which will scroll up and down the list:

```
Program: [UP]
« Q SIZE 1 -
   → s
  « IF N s >
      THEN s 1 +
       'N' STO
       "no more" 1 DISP
      ELSE Q N 1 + DUP
       'N' STO GET 3 DISP
       Q N 1 - GET 2 DISP
       Q N 2 - GET 1 DISP
     END
   >>
>>
Program: [DOWN]
« IF N 4 <
    THEN
     3 'N' STO
     "no more" 3 DISP
    ELSE
     Q N 1 - DUP
     'N' STO GET 3 DISP
    Q N 1 - GET 2 DISP
     Q N 2 - GET 1 DISP
   END
```

•

Classical Mechanics

In some statics problems you are working with a 3-space cartesian coordinate system and force vectors at various positions. The clue to solving a system of forces in equilibrium is that the sum of all forces acting on point is equal to zero.

Enter vectors like 3i - 4j + 5k in HP vector brackets like this [3 - 4 5]. That way, adding 2 vectors or multipling the vector by a scalar is easy.

Vector magnitude program

When you have a force vector out in space and have the coordinates for the head and the tail, one of the first things you can do is find the *Position Vector* which is the head coordinates minus the tail coordinates. So for example, you would enter the head coordinates [4 3 0] then the tail coordinates [3 5 8], then subtract. The result [1 -2 -8] is the *Position Vector* i -2j -8k. In order to use this to show the direction of a force, you need to make it a *Unit Vector* or a vector with magnitude = 1. You do this by simply dividing the *Position vector* by it's magnitude or length.

The following program finds the magnitude of a 3-space vector:

Example use: (program name: [MAG3])

Enter the 3-space vector on level 1.

3:

2:

[1 -2 -8]

Press [MAG3]: Result:

3:

2: [1 -2 -8]

1: 8.30662386292 This is the magnitude of the vector.

Now to get the Unit Vector just divide.

3:

2:

1: [.120385853086 -.240771706171 -.963086824686]

This is the Unit vector:

.120385853086i -.240771706171j -.963086824686k

```
program listing [MAG3]
« DUP 1 GET SQ → a
  « DUP 2 GET SQ → b
    « DUP 3 GET SQ
       a + b + [
                         <Remember, this is RPN!</pre>
    >>
  >>
>>
```

Coordinate direction angle program

When you have a unit vector representing the direction of a force vector whose tail is at the origin, you can find the Coordinate Direction Angles or the angles the vector makes with the x, y, and z axes. These angles are defined as:

```
alpha = Cos^{-1}(i of unit vector)
     beta = Cos^{-1}( j of unit vector)
     gamma = Cos^{-1}(k of unit vector)
Example use (program name: [CDA])
Enter the unit vector on level 1.
     3:
     2:
          [.120385853086 -.240771706171 -.963086824686]
     1:
Press [CDA].
The result is:
        [.120385853086 -.240771706171 -.963086824686]
    2:
        { 83.0856282278
        103.932091549
        164.383870595 }
```

On level 2 is your unit vector and on level 1 is the coordinate direction angles. This says that the vector makes a 83 degree angle with the X axis, a 103.9 degree angle with the Y axis, and a 164.38 degree angle with the Z axis.

program listing [CDA]

Interpolation program

When using tables (ie. steam tables or trig tables), many times the value your looking for is inbetween two other values. For example:

Steam table for saturated H2O

Temp.	Press.	etc
degC	kPa	
165	0.7005	
170	0.7917	

If you need the pressure at 167.5 degrees, you need to interpolate between the values. This would be:

```
P = 0.7005 + (167.5-165)/(170-165) * (0.7917-0.7005)= 0.7461 \text{ kPa}
```

Example use (program name: [INTPO])

```
Press [INTPO].

Type 165,.7005

170,.7917

167.5

Number you're trying to lookup

Press [CONT]
```

The program displays interpolated value for 167.5.

program listing [INTPO]

```
« CLLCD
                                         ⟨Clears LCD.
   "Enter LowLup, LLval"
                          1 DISP
                                         <Promts user.</pre>
        HighLup, HLval"
                          2 DISP
        YourLup "
                         3 DISP
   "Then hit [CONT]"
                         4 DISP
   HALT
                                     <Halts the program</pre>
   → a a1 b b1 x
                                      to allow user
      'a1 + (x-a)/(b-a) * (b1-a1)'
                                      to enter data.
>>
```

Timer program

Example use (program name [TIMER])

Enter starting time in seconds, press [TIMER]. Timer counts down and sounds alarm. Then press any key to stop alarm. Note: may not be extremely accurate but you can play around with a constant in the program to make it more accurate if you like.

program listing

```
    Set up error detection.

« IFERR
        «
          s 0 FOR t
               CLLCD "Timer running" 1 DISP
               t →STR 3 DISP
               "seconds" 4 DISP
                                     <Play with this
               .890 WAIT
                                     number to adjust
          -1 STEP
          51 CF
                                     accuracy.
          DO
               2000 .1 BEEP
               .1 WAIT
               2000 .1 BEEP
               .5 WAIT
          UNTIL KEY END
          51 SF
        >>
   THEN
     CLLCD
     "Enter seconds" 1 DISP
     "Press [TIMER]" 2 DISP
   END
>>
```

Lotto program

The lotto program picks 6 random numbers from 44. You can adapt this program for different lottos.

Example use (program name [LOTTO])

Press [LOTTO].

The program displays 6 numbers.

program lising

```
« 1 6 FOR X
     RAND 44 *
     0 FIX RND STD
     NEXT
     6 →LIST →STR
     DUP SIZE 2 -
     2 SWAP SUB
     2 DISP
     "Lotto numbers" 1 DISP
     " 3 DISP
```

Interest program

Given the principal, interest rate, number of times a year compounded, and number of years, this program calculates the total amount.

```
Example use (program name [INTEREST])
```

```
Enter principal amount. (ex. 10,000.00)
Enter interest rate. (ex. .085)
Enter number of times a year compounded.(ex. 12 times a year.)
Enter number of years left to accumulate.(ex. 5 years)
```

Press [INTEREST]

result:

15273.00 dollars.

program listing

Plot programs

The following programs make plotting a little easier.

Program [Draw]

This program takes an equation in the form of an expression off level 1, draws it, and stores the screen in global variable 'PT'. This same plot can then be instantly recalled later with the program [REDW].

program listing [Draw]

```
    'EQ' STO CLLCD
    DRAW LCD→ 'PT' STO
    PT →LCD DGTIZ
THEN
    DROP
    "Need equation on stack" 1 DISP
END

>>

program listing [REDW]

    Instantly redraws plot stored in 'PT'.

« PT →LCD DGTIZ >>

program listing [FAST]

For fast, low resolution plots.

« 2 RES >>
```

program listing [SLOW]

For slow, high resolution plots.

« 1 RES »

More Data Bank programs

These programs are simular to the previous data bank programs except these programs "page-flip" instead of scroll. Also when the program reaches the end of the list, it returns to the top (or bottom) and continues. The only catch is that when you make up your list of items, you must have a total number of items that are divisable by 3 (since it displays 3 at a time). This is no problem though, since you can just put in empty strings to take up the slack (i.e. " ").

Program name [Next] (Note this name must have some lower case letters to distinguish from the NEXT command word.)

listing

```
IFERR
         N 3 +
          'N' STO
          1 3 FOR r
               QNr+
               GET r DISP
         NEXT
    THEN
         0 'N' STO
         CLEAR
         1 3 FOR r
               QNr+
               GET r DISP
         NEXT
    END
»
```

Program name [PREV]

```
listing
« IFERR
     N3-
     'N' STO
     1 3 FOR r
          Q N r +
          GET r DISP
     NEXT
   THEN
     Q SIZE 3 - 'N' STO
     CLEAR
     1 3 FOR r
          Q N r +
          GET r DISP
     NEXT
   END
>>
Example list of items for previous programs:
{ "Joe Jones"
  "123 Main St."
  "ph. 123 4567"
  "Norman Bartfaster"
  "2345 E. West St."
  "ph. 345 5678"
  "This space for sale"
  "ph. 345 2345"
  "The End"
  11 11
}
```

Note the use of empty strings to fill out the "pages" and in particular to finish the last page. Remember you must have three items for each page.

Probability

Flip a coin until you get a head, and count the number of times, R, that you flipped. R could be 1, 2, 3, 4, and so on. Obviously, on the first flip, the probability of getting a head is .5. The chance of having to flip twice (R=2) to get a head is .5 x .5 or $(.5)^2$. You might guess that for an experiment like this the probability of getting a head after R flips is $(.5)^R$. Where R is the number of flips it took.

Probability Density Function of a random variable of the discrete type is denoted by f(x). It is the probability that an event occurs. It is also denoted by P(X=x), where X is the random variable and x is the specific number R, ex. P(X=2). Therefore in the experiment above:

$$p.d.f.$$
 $f(x) = P(X=x) = (.5)^{x}$.

Now, what if you needed to know the probabily of getting a head in 3 flips or less, ie. $P(X \le 3)$. This is the cumulative sum of all the probabilities less than or equal to three, and is formally called the Cumulative Distribution Function (c.d.f.). The c.d.f. is denoted by F(x) and is the following:

$$F(x) = P(X \le x) = \sum_{t=1}^{X} f(t)$$

Note that x can only be an integer, (discrete variable type).

Summation Program

END

```
Performs the following:
           \Sigma f(x)
           x = a
Example use (program name [ \Sigma FX ] )
Enter f(x) on stack as an expression.
     3:
     2:
     1:
            '.5^X'
                          note: capital letter X
Enter the bounds, a and b, you want the expression
summed over.
     3:
            '.5^X'
     2:
                                This is a.
                 3
     1:
                 5
                                This is b.
Press [ ΣFX ]
result:
     3:
     2:
             '.5^X'
                        <- left on stack</pre>
     1:
             .21875
                         <- This is the answer
program listing: ( [ \Sigma FX ] )
« IFERR

⟨Set up error detection
     → a b
                                to display a help screen.
      « 0 'ANS' STO
        a b FOR x
            x 'X' STO
            DUP →NUM
            'ANS' STO+
          NEXT
      ANS 'X' PURGE
      'ANS' PURGE
    THEN
      CLLCD
      "Enter 'expression' in" 1 DISP
      "terms of X, then enter" 2 DISP
      "summation bounds a,b" 3 DISP
```

```
Expected Value of X Program
(Mean of X)
     The expected value of X or E(X) is defined as:
           \sum x * f(x)
           x = a
program listing: ([ \( \Sigma XFX \) ])
« IFERR
     → a b
      « 0 'ANS' STO
        a b FOR x
            x 'X' STO
            DUP →NUM X * <Difference from summing
            'ANS' STO+
                                 program.
          NEXT
      >>
      ANS 'X' PURGE
      'ANS' PURGE
    THEN
      CLLCD
      "Enter 'expression' in" 1 DISP "terms of X, then enter" 2 DISP
```

"summation bounds a,b" 3 DISP

END

Binomial Distribution

The binomial distribution is a function given by:

$$P(a \le x \le b) = \sum_{k=a}^{b} [k!/(k!(n-k)!)] p^{k} (1-p)^{n-k}$$

With the mean = np, and variance = np(1-p), where n is the number of Bernoulli trials, and p is the probability of success.

Example use

The probability that a part fails during the first year of operation is 0.05. What is the probability that out of 10 parts, between 3 and 5 are defective?

In this case n = 10, p = 0.05, a = 3, and b = 5.

Type 10,.05,3,5 on command line.

```
Press [BIN]
```

```
result:
```

3:

2:

1: 1.15008027966E-2

program listing [BIN]

```
« IFERR
```

```
→ n p a b
  « 0 'ANS' STO
     a b FOR y
         n y COMB
         p^y*(1-p)^(n-y) EVAL *
         'ANS' STO+
     NEXT
```

ANS 'ANS' PURGE

"→ n,p,a,b" 1 DISP **END**

error.

Poisson Distribution

The Poisson distribution is a function given by:

$$P(a \le x \le b) = \sum_{k=a}^{b} (L^k e^{-L})/k!$$

where L = np = mean. The approximation works well when the probability of success, p, is small and the number of trials, n, is large.
(The greek letter lambda is usually used in place of L.)

Example use

The probability that a part is defective is 0.02. what is the probability that out of 200 parts, between 10 and 15 parts are defective?

In this case lambda = np = 200(0.02) = 4, a = 10, and b = 15.

Type 4,10,15 on command line.

Press [POISS]

The answer is about .008127.

```
program listing [POISS]
```

Normal Distribution

Unlike the previous distributions which were discrete types, the normal distribution is a continuous type. The normal distribution with mean = 0 and variance = 1 is given by:

$$P(Z < z) = I(z) = \int_{-i \text{ in finity}}^{z} [e^{-z^2/2}]/\Gamma(2\pi)$$

and is denoted N(0,1).

Example use

Whats the probability of Z<.7?

Type .7 on command line.

Press [NRM]

answer: .758

program listing [NRM]

" → b " 1 DISP END

THEN

»

Another version of this program can take upper and lower bounds and compute the probability. (i.e. $P(a \le X \le b)$)

program listing [NRM2]

Pooled Variance

Pooled variance is used in many Statistical methods such as confidence intervals and hypothesis tests. The following program computes this.

program listing

```
« IFERR

→ s1 s2 n1 n2

« '((n1-1)*s1+(n2-1)*s2)/(n1+n2-2)'

→NUM DUP 3 DISP

"Pooled variance =" 2 DISP

»

THEN

"Pooled variance" 1 DISP

"Enter var1, var2, n1, n2" 2 DISP

END
»
```

Parallel resistance program

Example use (program name: [P.RES])

Enter the values of resisters.

470,1000,100,390,560 [ENTER]

Enter the number of resisters you entered.

5 [ENTER]

Press [P.RES]

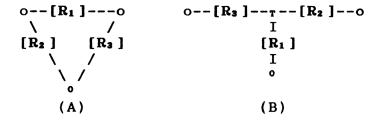
The equivalent resistance of (in this case) the 5 resisters is displayed.

program listing [P.RES]

Delta to Y network transformation

The resister network (A) is called a delta network. It can be transformed into a Y network, (B), with the following formulas:

 $R_{1\,Y} = R_2 * R_3 / (R_1 + R_2 + R_3)$ The R's on the right side of $R_{2\,Y} = R_1 * R_3 / (R_1 + R_2 + R_3)$ equation are from the delta $R_{3\,Y} = R_1 * R_2 / (R_1 + R_2 + R_3)$ network.



Notice the pattern of the transformed resisters.

Example use (program name: [D.Y])

Enter R_1 , R_2 , and R_3 from delta network on stack.

3: 470 R_1 2: 100 R_2 1: 180 R_3

Press [D.Y]

The program returns the R_1 , R_2 , and R_3 for the Y network.

3: 24 R₁ 2: 112.8 R₂ 3: 62.66667 R₃

program listing [D.Y]

Y to Delta network transformation

This program does the reverse of the Delta to Y program. See Delta to Y program for more details.

program listing name: [Y.D]

Angular frequency and frequency conversion programs

The following program converts angular frequency (rad/s) to frequency (Hz).

program listing: name: [W→F]

 $\ll \rightarrow w$ $\ll {}^{\dagger}w/(2 * \pi) {}^{\dagger} \rightarrow NUM \gg$

The following program converts frequency (Hz) to angular frequency (rad/s).

program listing: name: [F→W]

```
Complex
                Impedence converter
programs
     This program converts a resistance into it's
complex impedence Z<sub>R</sub>. Input: resistance (ohms).
Example: enter 1000 for a 1k resistor.
Example output:
                  (1000,0)
     This is the complex number 1000 + 0j.
program listing: name: [RESI]
« IFERR
   → r
      « r 0 R→C »
  THEN
    " Need resistance " 1 DISP
  END
     The following program converts a capacitance into
it's complex impedence Zc. Input: angular frequency
(rad/s), capacitance (F).
program listing: name: [CAP]
« IFERR
   → W C
      « w c * INV NEG O SWAP R+C »
  THEN
     " Need angular freq.," 1 DISP
           capacitance " 2 DISP
  END
>>
     The following program converts an inductance into
it's complex impedence Z<sub>L</sub>. Input: angular frequency
(rad/s), inductance (H).
program listing: name: [IDUCT]
« IFERR
      → w L
          « w L * 0 SWAP R→C »
 THEN
    " Need angular freq.," 1 DISP
```

inductance " 2 DISP

END

Evaluating Boolean Expressions

The HP-28 can evaluate boolean expressions. The following example describes the process.

Suppose you have a 3 input function with the following output:

<u>A</u>	В	C	F
0	0	0	0
0	0	1	1
0	1	0	1
0	1	1	0
1	0	0	0
1	0	1	0
1	1	0	1
1	1	1	0

The boolean expression from the truth table is:

$$A'B'C + A'BC' + ABC'$$

To verify this expression, the values of A, B, and C must first be stored in global variables.

Looking at A, B, and C on the truth table from bottom to top we have:

A = 11110000 B = 11001100

C = 10101010

Go into the binary menu and select [BIN] mode.

Enter the numbers (must use the pound symbol) and store each one under A, B, and C respectfully.

Then you can use the AND OR and NOT operators (also under binary menu) to evaluate the expression. For the example above, you would key in:

A [NOT] B [NOT] C [ENTER] [AND] [AND]
A [NOT] B [ENTER] C [NOT] [AND] [AND] [OR]
A [ENTER] B [ENTER] C [NOT] [AND] [AND] [OR]

The result should be the output of the truth table 01000110.

RLC circuit programs

Damping factor and undamped angular frequency 2 for RLC circuits.

This program calculates two important variables used in determining the natural and step responses of basic parallel and series RLC circuits. They are the damping factor \ll (or neper frequency) and the undamped angular frequency ω_0 (or resonant radian frequency). This program calculates ω_0^2 not ω_0 .

example use (program name [RLC])

The program takes four values R, L, C and x. The x is a 0 or 1 which indicates to the program whether the circuit is a series RLC or parallel RLC. x is 0 for parallel, and x is 1 for series.

If, for example R=400 ohms, L=.04H, C=1uf are the componet values for a parallel RLC circuit, enter the values of R, L and C on stack in this order.

400, .04, 1E-6 [ENTER]

Now enter a zero on the stack to indicate a parallel circuit.

0 [ENTER]
Press [RLC]

The program displays the value of \ll and ω_0^2 .

program listing: name: [RLC]

```
« IFERR
```

```
\rightarrow r L c x
                                     <- Note: L is local</pre>
    \ll 'r*INV(2*L)' EVAL \rightarrow a
         'INV(2*r*c)' EVAL \rightarrow b
             'INV(L*c)' EVAL \rightarrow c
             « IF x 1 ==
               THEN
                  "Series RLC" 1 DISP
                  "alpha=" a →STR + 2 DISP
                  a c
               ELSE
                  "Parallel RLC" 1 DISP
                  "alpha=" b →STR + 2 DISP
               END
               "wo^2=" c \rightarrow STR + 3 DISP
  » » »
THEN
   "Need R,L,C,x" 1 DISP
   "where x=0 for parallel," 2 DISP
   "x=1 for series RCL." 3 DISP
END
```

Determining expressions for basic RLC circuits.

Natural and step responses for parallel and series RLC circuits all have the same basic functions for 3 cases. The cases are overdamped, underdamped, and critically damped.

For the overdamped case:

$$f(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$$

$$f(0) = A_1 + A_2$$

$$df(0)/dt = S_1 A_1 + S_2 A_2$$

For the underdamped case:

$$f(t) = e^{-at} [B_1 \cos(\omega_d t) + B_2 \sin(\omega_d t)]$$

$$f(0) = B_1$$

$$df(0)/dt = \omega_d B_2 - aB_1$$

For the critically damped case:

$$f(t) = e^{-at} [D_1 t + D_2]$$

$$f(0) = D_2$$

$$df(0)/dt = D_1 - aD_2$$

Note: a = < (damping factor)

f(t) can be v(t) or i(t) for the natural response and for the step response the final value, v_f or i_f , is added to the expression

This program takes the values of « and ω_0 ² and determines if the response is overdamped, underdamped, or critically damped and calculates the parameters S_1 and S_2 if overdamped, « (a) and ω_d if underdamped, and « (a) if critically damped. These values can then be used in the f(t) expressions above and the coefficients $(A_1,A_2,B_1,$ etc.) can then be determined from initial conditions.

```
example use (program name: [SSAW])
```

You have a series RLC circuit with R=560 ohms, L=.1H and C=.1uf. The initial conditions of $V_{\text{cap}}=100v$ and i=0 at t=0 is given. Find the natural response i(t) for t>0?

First, \prec and $\omega_0^{\ 2}$ is determined by using the [RLC] program.

Type 560, .1, .1E-6, 1 on command line.

Press [RLC]

The display shows:

Series RLC alpha=2800 wo^2=100000000

Now press [SSAW]

The display shows:

Underdamped. alpha= 2800 and wd= 9600

This tells you that the response is underdamped so you'll have to use the underdamped function:

 $i(t) = e^{-at} [B_1 \cos(\omega_d t) + B_2 \sin(\omega_d t)]$

Substituting \ll and ω_d :

 $i(t) = e^{-2800t} [B_1 \cos(9600t) + B_2 \sin(9600t)]$

 B_1 and B_2 can then be determined from initial conditions.

```
program listing name: [SSAW]
\ll IFERR \rightarrow a w
       \ll '-a+\Gamma(a^2-w)' EVAL \rightarrow y
             \ll IF y IM 0 \Rightarrow
               THEN
                   CLLCD
                   "Underdamped. alpha=" 1 DISP
                   y RE NEG 2 DISP
"and wd=" 3 DISP
                   y IM 4 DISP
               ELSE
                   -a-\Gamma(a^2-w) EVAL \rightarrow z
                   \ll IF y z ==
                     THEN
                         "Critically damped." 1 DISP
                         "alpha=" 2 DISP
                         z NEG 3 DISP
                     ELSE
                         "Overdamped. S1=" 1 DISP
                         y 2 DISP
                         "and S2=" 3 DISP
                         z 4 DISP
                     END
                   >>
               END
      >>
   THEN
      "Need alpha, wo^2" 1 DISP
   END
>>
```

Quickies

Program name [ON] Turns on sound. Input: none.

« 51 CF »

Program name [OFF] Turns off sound. Input: none.

« 51 SF »

Program name [DEGK] Converts degrees Celsius to degrees Kelvin. Input: number representing degrees in Celsius.

 $\ll 273.15 + \gg$

Program name [MODE] Toggles between standard mode and fixed, 2 decimal place mode. Input: none.

« IF 49 FC? THEN 2 FIX ELSE STD END »

Program name [-VECT] Puts 3 numbers into a 3-space vector.

Input: 3 numbers.

« 3 →ARRY »

Program name [ROT3] Rotates 3 numbers on stack. Input: 3 number's on stack.

« 3 ROLL 3 ROLL »

Program name [RTN] Returns you to the home directory. Input: none.

« HOME »

Program name [KILO] Multiplies a number by 1000. Input: a number on the stack.

« 1000 * »

Program name [MICR] Divides a number by 10⁶. Input: a number on the stack.

« .000001 * »